## A note on twisting type-N solutions

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## LETTER TO THE EDITOR

## A note on twisting type- $\boldsymbol{N}$ solutions

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Received 8 January 1980


#### Abstract

It is shown that the twisting type- $N$ equations for empty space derived by Hauser are a special case of the equations given by Robinson et al.


A family of algebraically special vacuum metrics in which the degenerate principal null direction is twisting was presented by Robinson and co-workers (Robinson and Robinson 1969, Robinson et al 1969). In his survey of exact solutions of the Einstein field equations, Kinnersley (1975) stated that an assumption which leads to the Robinson et al metrics is that the Riemann tensor falls off asymptotically as $p^{-3}$, thus excluding radiative solutions. Robinson (1975) has shown that solutions may be obtained from Robinson et al in which the Riemann tensor falls off like $\rho^{-2}$. In fact, among the Robinson et al metrics are some for which the Riemann tensor falls off like $\rho^{-1}$, although these are not explicitly exhibited. These metrics are therefore of type $N$ in the Petrov classification and contain Hauser's $(1974,1978)$ one-parameter family of twisting type- $N$ gravitational fields.

Robinson et al have shown that, if a space-time admits a null vector field $k^{i}$ ( $i=1,2,3,4$ ) tangent to a shear-free diverging congruence of affinely parametrised null geodesic curves, then coordinates $x^{i}=(\zeta, \bar{\zeta}, \sigma, \rho)$ may be chosen such that the lineelement built around the congruence has the form

$$
\begin{align*}
& \mathrm{d} s^{2}=2 P \bar{P} \mathrm{~d} \zeta \mathrm{~d} \bar{\zeta}+2 \mathrm{~d} \Sigma(\mathrm{~d} \rho+Z \mathrm{~d} \zeta+\bar{Z} \mathrm{~d} \bar{\zeta}+S \mathrm{~d} \Sigma),  \tag{1a}\\
& \mathrm{d} \Sigma=a(\Omega \mathrm{~d} \zeta+\bar{\Omega} \mathrm{d} \bar{\zeta}+\mathrm{d} \sigma)=k_{i} \mathrm{~d} x^{i}, \tag{1b}
\end{align*}
$$

with $a$ and $\Omega$ independent of $\rho$, and a bar denoting complex conjugation. For any function $f(\zeta, \bar{\zeta}, \sigma)$ we use the notation

$$
\begin{equation*}
\mathrm{D} f=\partial f / \partial \zeta-\Omega \dot{f}, \quad \overline{\mathrm{D}} f=\partial f / \partial \bar{\zeta}-\bar{\Omega} \dot{f} \tag{2}
\end{equation*}
$$

where a dot indicates partial differentiation with respect to $\sigma$.
The vacuum field equations for type- $N$ solutions are satisfied provided

$$
\begin{align*}
& P=\mathrm{e}^{u}(\rho+\mathrm{i} \omega),  \tag{3a}\\
& Z=\rho \Lambda-\mathrm{i}(\mathrm{D}+\Lambda) \omega,  \tag{3b}\\
& S=a^{-1} \rho \dot{u}-\frac{1}{2} K, \tag{3c}
\end{align*}
$$

with $u=u(\zeta, \bar{\zeta}, \sigma)$ and

$$
\begin{equation*}
\omega=\frac{1}{2} \mathrm{i} a \mathrm{e}^{-2 u}(\mathrm{D} \bar{\Omega}-\overline{\mathrm{D}} \Omega), \tag{4a}
\end{equation*}
$$

$$
\begin{align*}
& \Lambda=\mathrm{D}(\log a)-\dot{\Omega},  \tag{4b}\\
& K=\mathrm{e}^{-2 u}[\overline{\mathrm{D}}(\Lambda-\mathrm{D} u)+\mathrm{D}(\bar{\Lambda}-\overline{\mathrm{D}} u)] \tag{4c}
\end{align*}
$$

If we also define

$$
\begin{equation*}
J=(\mathrm{D}+\Lambda-\mathrm{D} u)(\Lambda-\mathrm{D} u), \tag{5}
\end{equation*}
$$

then the basic functions $a, \Omega, \bar{\Omega}, u$ must satisfy

$$
\begin{align*}
& K \omega+\frac{1}{2} \mathrm{e}^{-2 u}[(\overline{\mathrm{D}}+\bar{\Lambda})(\mathrm{D}+\Lambda)+(\mathrm{D}+\Lambda)(\overline{\mathrm{D}}+\bar{\Lambda})] \omega=0,  \tag{6a}\\
& \stackrel{\mathrm{D}}{ } J=0=\mathrm{D} \bar{J} . \tag{6b}
\end{align*}
$$

Introducing the function $U(\zeta, \bar{\zeta}, \sigma)$ satisfying

$$
\begin{equation*}
\dot{U}=a \mathrm{e}^{-u} \tag{7}
\end{equation*}
$$

it can be shown that (5) and (6a) are equivalent to

$$
\begin{align*}
& a J=\mathrm{e}^{u}\left(\mathrm{D}^{2} U\right)^{\cdot}  \tag{8a}\\
& \left(\overline{\mathrm{D}}^{2} \mathrm{D}^{2}-\mathrm{D}^{2} \overline{\mathrm{D}}^{2}\right) U=0 \tag{8b}
\end{align*}
$$

and, provided ( $6 b$ ) is satisfied, one can prove that

$$
\begin{equation*}
\left(\overline{\mathrm{D}}^{2} \mathrm{D}^{2} U\right)^{\cdot}=\left(\mathrm{D}^{2} \overline{\mathrm{D}}^{2} U\right)^{\cdot}=a \mathrm{e}^{-u} J \bar{J}, \tag{9}
\end{equation*}
$$

thus showing that the left-hand side of $(8 b)$ is independent of $\sigma$.
The twist of the vector field $(1 b)$ is given by $-\omega /\left(\rho^{2}+\omega^{2}\right)$. Clearly the twist vanishes if $\omega=0$. The only non-vanishing tetrad components of the Riemann tensor is, in Newman and Penrose (1966) notation,

$$
\begin{equation*}
\Psi_{4}=\left[-\mathrm{e}^{-2 u} /(\rho+\mathrm{i} \omega)\right] a^{-1} \dot{J} \tag{10}
\end{equation*}
$$

The coordinate transformations which leave invariant the form (1a) of the metric are products of the trivial transformation

$$
\begin{equation*}
\zeta \rightarrow \bar{\zeta}, \quad \bar{\zeta} \rightarrow \zeta, \quad \rho \rightarrow \rho, \quad \sigma \rightarrow \sigma \tag{11}
\end{equation*}
$$

with

$$
\begin{equation*}
\zeta \rightarrow f(\zeta), \quad \bar{\zeta} \rightarrow \bar{f}(\bar{\zeta}), \quad \rho \rightarrow \rho, \quad \sigma \rightarrow \sigma \tag{12}
\end{equation*}
$$

and

$$
\begin{equation*}
\zeta \rightarrow \zeta, \quad \bar{\zeta} \rightarrow \bar{\zeta}, \quad \rho \rightarrow \rho g(\zeta, \bar{\zeta}, \sigma), \quad \sigma \rightarrow h(\zeta, \bar{\zeta}, \sigma), \tag{13}
\end{equation*}
$$

where $f^{\prime}, \overline{f^{\prime}}, g$ and $\dot{h}$ are non-zero. The first transformation is essentially complex conjugation. Invariance under the other two follows directly from the invariance of

$$
\begin{equation*}
P \bar{P} \mathrm{~d} \zeta \mathrm{~d} \bar{\zeta}, \quad \rho \mathrm{~d} \Sigma, \quad \rho^{-1}(\mathrm{~d} \rho+Z \mathrm{~d} \zeta+\bar{Z} \mathrm{~d} \bar{\zeta}+S \mathrm{~d} \Sigma) \tag{14}
\end{equation*}
$$

under (12) and (13).
We can use (12) and (13) to eliminate some of the functions $a, \Omega, \bar{\Omega}, u$, restricting the transformations at our disposal accordingly. If $\omega$ vanishes we can take $\Omega=\bar{\Omega}=0$. Under the transformations (12) and (13)

$$
\begin{equation*}
a \rightarrow a / g \dot{h}, \quad u \rightarrow u-\frac{1}{2} \log \left(f^{\prime} \bar{f}^{\prime} g^{2}\right) . \tag{15}
\end{equation*}
$$

Clearly we can specialise the coordinates $\rho$ and $\sigma$ so that

$$
\begin{equation*}
a=1 \quad \text { with } g \dot{h}=1 \tag{16}
\end{equation*}
$$

or

$$
\begin{equation*}
u=0 \quad \text { with } g^{2} f^{\prime} f^{\prime}=1 \tag{17}
\end{equation*}
$$

or both.
The type- $N$ field equations ( $6 a$ ) and ( $6 b$ ) correspond to equations (20) and (21) respectively of Hauser (1978). Imposing condition (17) we find that the two pairs of equations are identical, with Hauser's (1978) D, $\mathrm{D}^{*}, \Delta, \mathscr{D}, \mathscr{D}^{*}, p$ and $h$ corresponding to our $\mathrm{D}, \overline{\mathrm{D}}, a^{-1} \omega, \mathrm{D}-\dot{\Omega}, \overline{\mathrm{D}}-\bar{\Omega}, a$ and $-J$ respectively. Hauser's $(1974,1978)$ twisting type- $N$ solution (the only one presently known) was obtained by choosing $\Omega=\mathrm{i}(\zeta+\bar{\zeta})$ and computing the successive integrability conditions on the type $-N$ field equations. This yields for the function $a$ which appears in ( $1 b$ ) the solution $a=\left(\xi^{2}\right)^{3 / 4} f(y)$, where $\sqrt{2} \xi=\zeta+\bar{\zeta}, y=\sigma / \xi^{2}$ and $f(y)$ satisfies the equation

$$
\begin{equation*}
\mathrm{d}^{2} f / \mathrm{d} y^{2}+3 f / 16\left(1+y^{2}\right)=0 \tag{18}
\end{equation*}
$$

Finally, imposing the further restriction (16) on the metric, the type- $N$ field equations ( $6 a$ ) and ( $6 b$ ) reduce to the relatively simple form

$$
\begin{align*}
& \overline{\mathrm{D}} \frac{\partial}{\partial \sigma}(\mathrm{D} \Omega)=0  \tag{19a}\\
& \left(\overline{\mathrm{D}}^{2} \mathrm{D}-\mathrm{D}^{2} \overline{\mathrm{D}}\right) \Omega=0 \tag{19b}
\end{align*}
$$

Equation (49) of Kinnersley (1975) contains type- $N$ field equations which are due to A Exton (private communication). The first of these agrees with (19a). The second, however, is different from (19b), being of lower order.

I wish to thank Dr P A Hogan for helpful comments.

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